

ENGINE

Teaching online electronics, microcontrollers and programming in Higher Education

Programming of embedded systems

6. Neopixels driver

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Programing of embedded systems

6. Neopixels driver

Declaration

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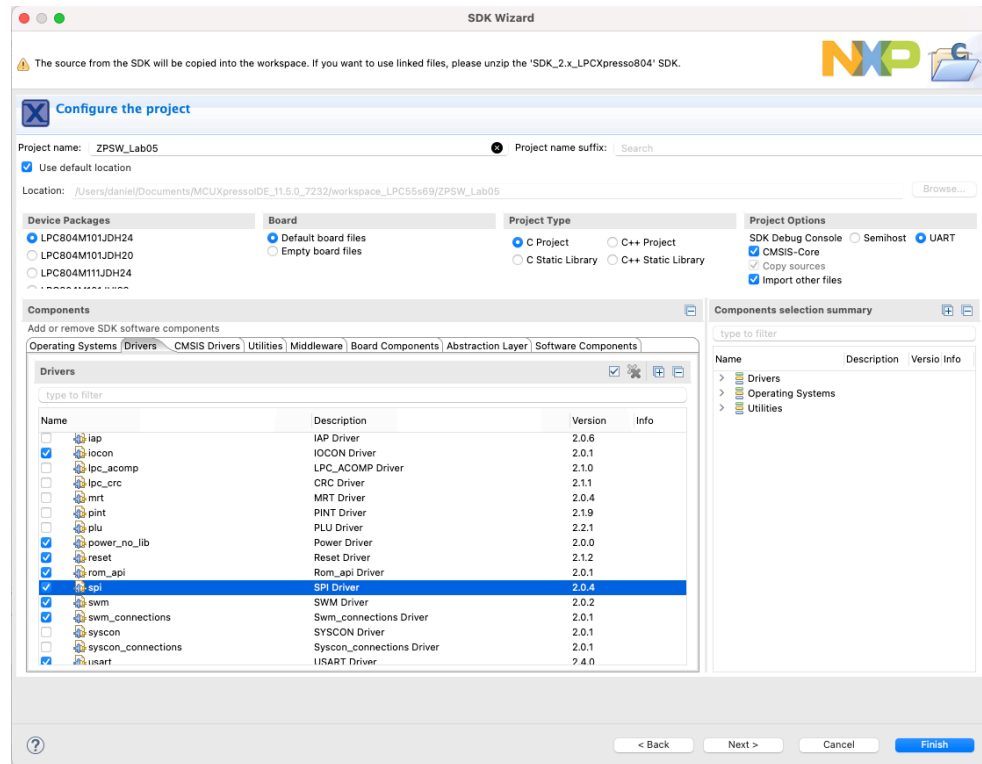
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Programming of embedded systems

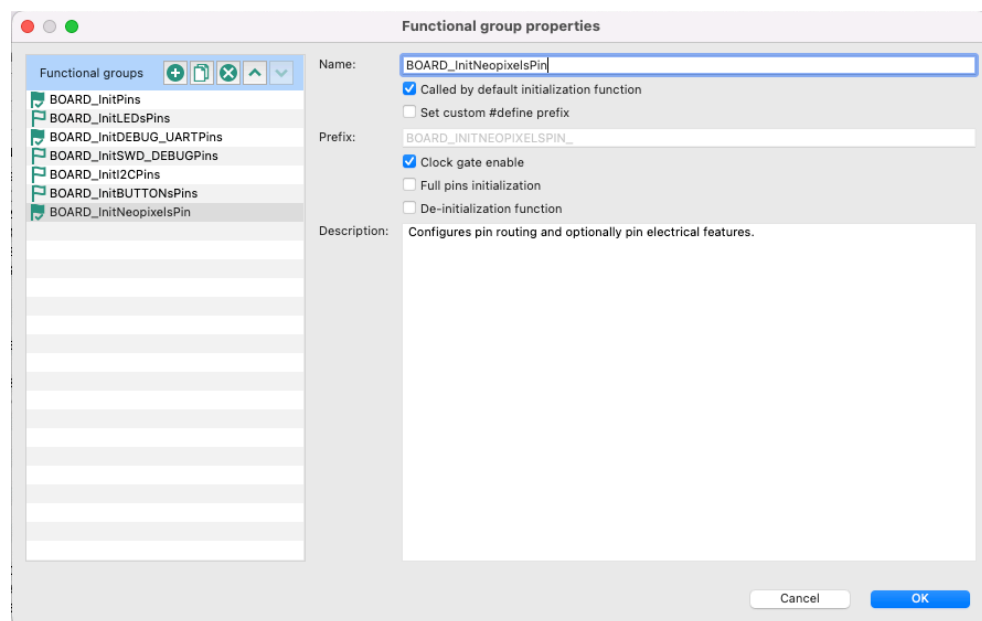
6. Neopixels driver

I. Using the SPI interface

1. Create a new project for the *LPCXpresso804* board and name it eg *Lab06*.
2. Add *SPI* driver:



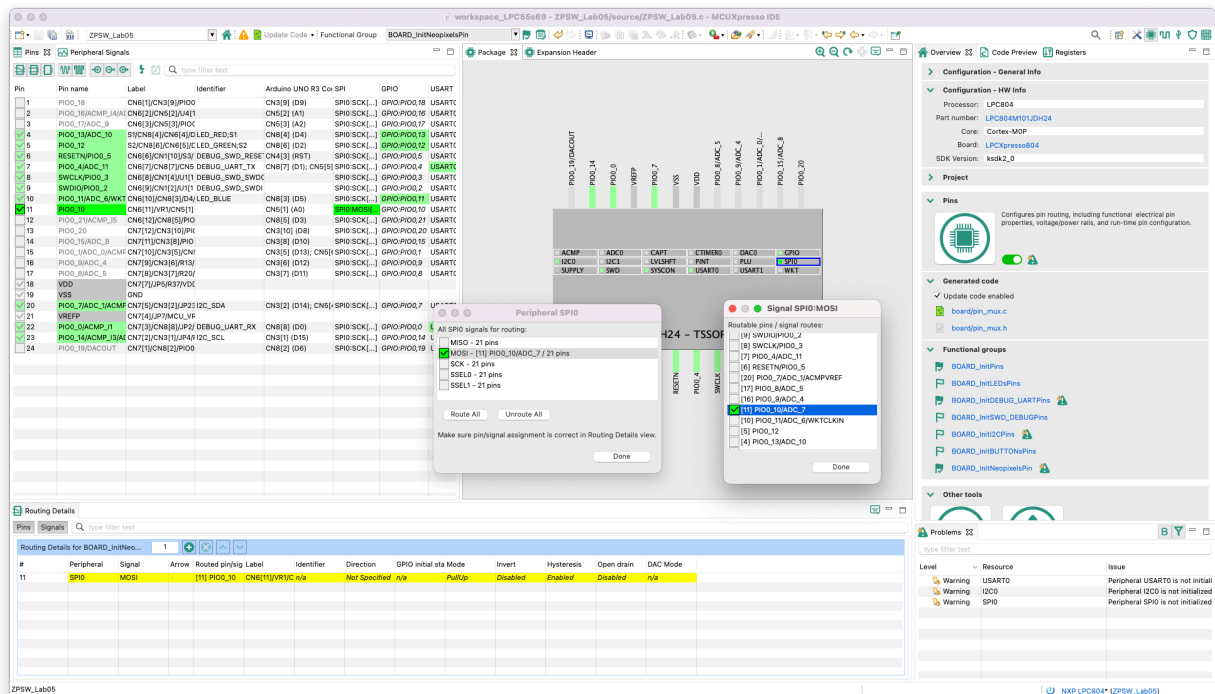
3. Go to *Config Tool* -> *Pins* and then in the *Functional group* create a new preset *BOARD_InitNeopixelsPin*:



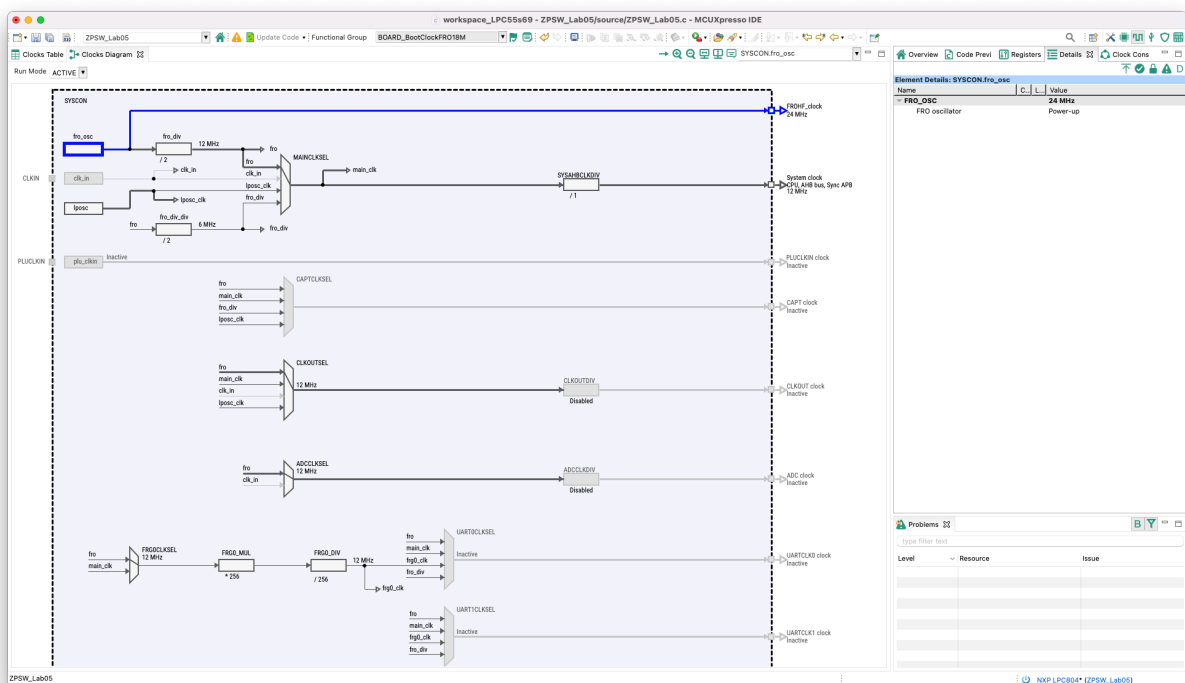
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4. Connect the *MOSI* line of the *SPIO* interface to the *PIO_010* pin of the microcontroller:



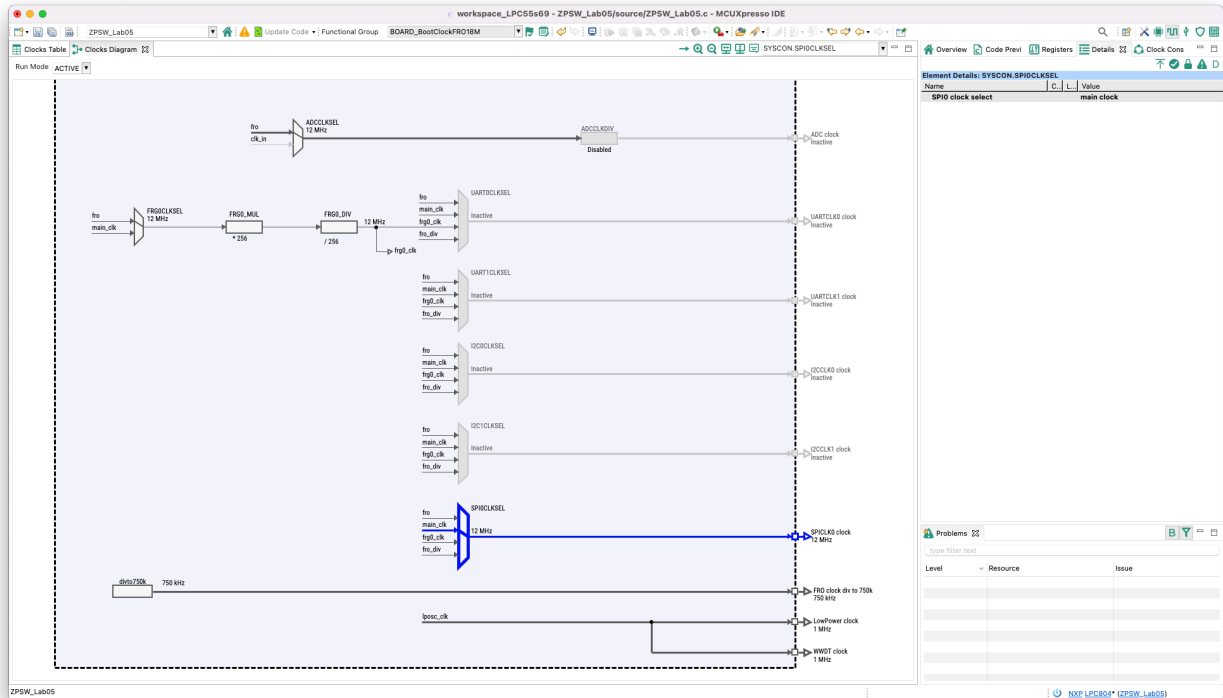
5. In the Clocks tab, click on the *FRO_OSC* oscillator block and change its frequency to 24 MHz:



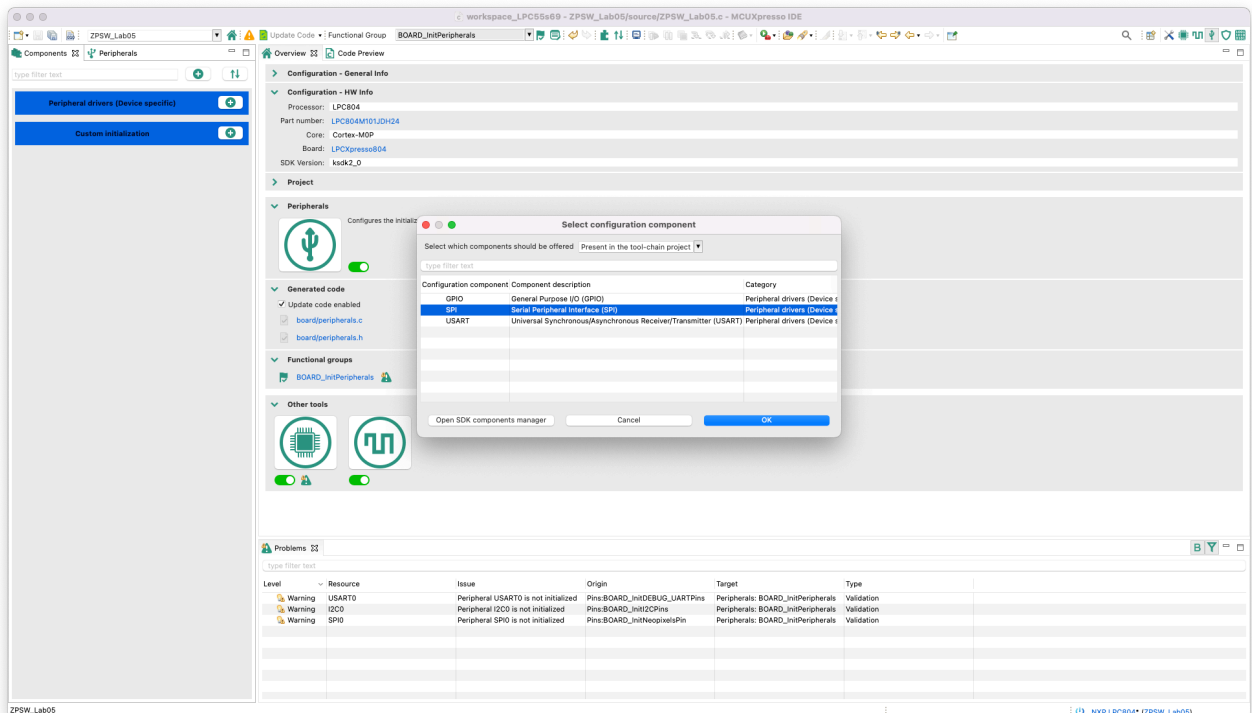
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- Then bring the 12 MHz clock signal to the *SPI0* interface by selecting *main_clk* in the *SPI0CLKSEL* block:



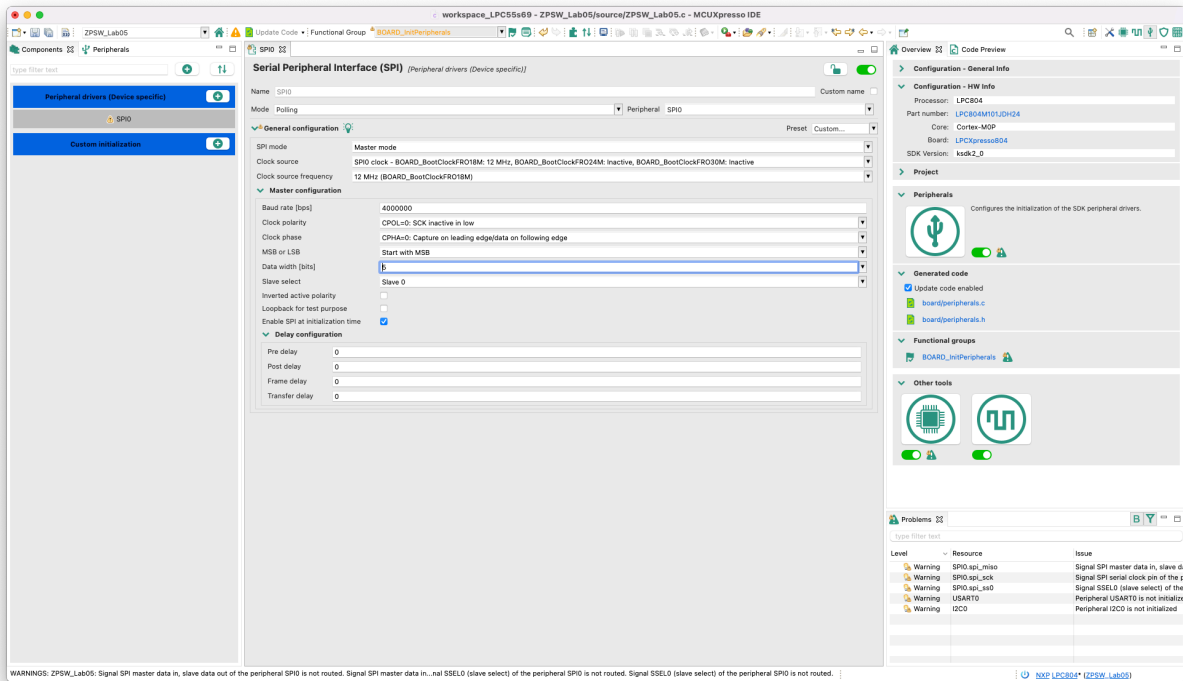
- In the *Peripherals* tab, select the *SPI* driver:



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8. Configure SPI transmission parameters in *Polling mode* for the SPI0 interface:



9. Go to the main project file and modify the code as below:

```
#include <stdio.h>
#include "board.h"
#include "peripherals.h"
#include "pin_mux.h"
#include "clock_config.h"
#include "LPC804.h"
#include "fsl_debug_console.h"

#define LEDS 37
#define GET_BIT(k, n) (k & (1 << (n)))
#define SET_BIT(k, n) (k |= (1 << (n)))
#define CLR_BIT(k, n) (k &= ~(1 << (n)))

#define CODE_0 0b10000
#define CODE_1 0b11100

uint32_t colors[LEDS]={0};

void Neopixels_Send(SPI_Type *base, uint32_t n, uint32_t *value) {
    uint16_t LED_data=0;

    for(int j=0;j<n;j++) {
        for(int i=23;i>=0;i--) {
            LED_data = GET_BIT(value[j], i) ? CODE_1 : CODE_0;

            while(!(base->STAT & SPI_STAT_TXRDY_MASK));
            base->TXDAT = LED_data ;
        }
        // Reset >= 50 us
        LED_data=0;
        for(int j=0;j<50;j++) {
            while(!(base->STAT & SPI_STAT_TXRDY_MASK));
            base->TXDAT = LED_data ;
        }
    }
}

/*
 * @brief Application entry point.
 */
int main(void) {

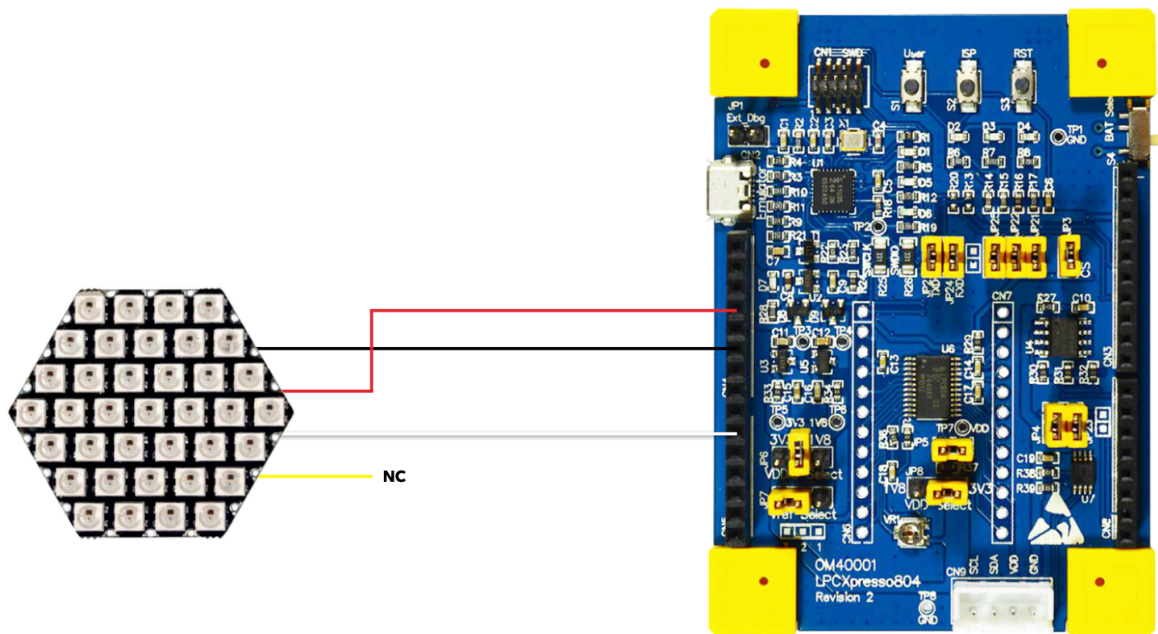
    /* Init board hardware. */
    BOARD_InitBootPins();
    BOARD_InitBootClocks();
    BOARD_InitBootPeripherals();
#ifdef BOARD_INIT_DEBUG_CONSOLE_PERIPHERAL
    /* Init FSL debug console. */
    BOARD_InitDebugConsole();
#endif
}
```

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```
SPI_WriteConfigFlags(SPI0_PERIPHERAL, kSPI_ReceiveIgnore);  
  
while(1) {  
    colors[18] = 0x00000F;  
    Neopixels_Send(SPI0_PERIPHERAL, LEDS, colors);  
}  
return 0 ;  
}
```

10. Connect the LED module to the prototype board according to the diagram below:



11. Build the project in the **Release** configuration, program the microcontroller and check the program operation.

ATTENTION! Do not turn on all the LEDs with full brightness without additional power supply to the module - it may damage the on board stabilizer. The prototype board is able to power the entire LED module with approx. 1/16 brightness - the maximum value for the white color: **HEX 0x0F0F0F**.
DEC R: 15, G: 15, B: 15

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II. Function `setRGB`

1. Write a function that sets the color in RGB 888 format.
2. Add a system timer and check the brightness adjustment of individual RGB components:

```
#include <stdio.h>
#include "board.h"
#include "peripherals.h"
#include "pin_mux.h"
#include "clock_config.h"
#include "LPC804.h"
#include "fsl_debug_console.h"

#define LEDS 37
#define GET_BIT(k, n)    (k & (1 << (n)))
#define SET_BIT(k, n)    (k |= (1 << (n)))
#define CLR_BIT(k, n)    (k &= ~(1 << (n)))

#define CODE_0           0b10000
#define CODE_1           0b11100

uint32_t colors[LEDS]={0};
uint8_t k=0;

void Neopixels_Send(SPI_Type *base, uint32_t n, uint32_t *value) {
    uint16_t LED_data=0;

    for(int j=0;j<n;j++) {
        for(int i=23;i>=0;i--) {
            LED_data = GET_BIT(value[j], i) ? CODE_1 : CODE_0;

            while(!(base->STAT & SPI_STAT_TXRDY_MASK));
            base->TXDAT = LED_data ;
        }
        // Reset >= 50 us
        LED_data=0;
        for(int j=0;j<50;j++) {
            while(!(base->STAT & SPI_STAT_TXRDY_MASK));
            base->TXDAT = LED_data ;
        }
    }
}

inline uint32_t setRGB(uint8_t r, uint8_t g, uint8_t b) {
    return ((g<<16) | (r<<8) | b);
}

void SysTick_Handler(void) {
    colors[k] = setRGB(k++, 0, 0);
    //colors[k] = setRGB(0, k++, 0);
    //colors[k] = setRGB(0, 0, k++);
    Neopixels_Send(SPI0_PERIPHERAL, LEDS, colors);
}

/*
 * @brief Application entry point.
 */
int main(void) {
    /* Init board hardware. */
    BOARD_InitBootPins();
    BOARD_InitBootClocks();
    BOARD_InitBootPeripherals();
#ifdef BOARD_INIT_DEBUG_CONSOLE_PERIPHERAL
    /* Init FSL debug console. */
    BOARD_InitDebugConsole();
#endif

    SPI_WriteConfigFlags(SPI0_PERIPHERAL, kSPI_ReceiveIgnore);

    SysTick_Config(SystemCoreClock / 100); // 100 Hz

    while(1) {
    }
    return 0 ;
}
```

3. Build a project, program the layout and test the program.

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II. Function `setBrightness`

1. Write a function that sets the brightness of a given color:

```
#include <stdio.h>
#include "board.h"
#include "peripherals.h"
#include "pin_mux.h"
#include "clock_config.h"
#include "LPC804.h"
#include "fsl_debug_console.h"

#define LEDS 37
#define GET_BIT(k, n) (k & (1 << (n)))
#define SET_BIT(k, n) (k |= (1 << (n)))
#define CLR_BIT(k, n) (k &= ~(1 << (n)))

#define CODE_0 0b10000
#define CODE_1 0b11100

uint32_t colors[LEDS]={0};
uint8_t k=0;

void Neopixels_Send(SPI_Type *base, uint32_t n, uint32_t *value) {
    uint16_t LED_data=0;

    for(int j=0;j<n;j++) {
        for(int i=23;i>=0;i--) {
            LED_data = GET_BIT(value[j], i) ? CODE_1 : CODE_0;

            while(!(base->STAT & SPI_STAT_TXRDY_MASK));
            base->TXDAT = LED_data ;
        }
    }
    // Reset >= 50 us
    LED_data=0;
    for(int j=0;j<50;j++) {
        while(!(base->STAT & SPI_STAT_TXRDY_MASK));
        base->TXDAT = LED_data ;
    }
}

inline uint32_t setRGB(uint8_t r, uint8_t g, uint8_t b) {
    return ((g<<16) | (r<<8) | b);
}

uint32_t setBrightness(uint32_t color, uint8_t level) {
    uint8_t b = level * (color & 0x0000FF) / 255;
    uint8_t r = level * ((color & 0x00FF00) >> 8) / 255;
    uint8_t g = level * ((color & 0xFF0000) >> 16) / 255;

    return ((g<<16) | (r<<8) | b);
}

void SysTick_Handler(void) {
    colors[18] = setRGB(255, 0, 128);
    colors[18] = setBrightness(colors[18], k++);

    Neopixels_Send(SPI0_PERIPHERAL, LEDS, colors);
}

/*
 * @brief Application entry point.
 */
int main(void) {
    /* Init board hardware. */
    BOARD_InitBootPins();
    BOARD_InitBootClocks();
    BOARD_InitBootPeripherals();
#ifdef BOARD_INIT_DEBUG_CONSOLE_PERIPHERAL
    /* Init FSL debug console. */
    BOARD_InitDebugConsole();
#endif

    SPI_WriteConfigFlags(SPI0_PERIPHERAL, kSPI_ReceiveIgnore);

    SysTick_Config(SystemCoreClock / 100); // 100 Hz

    while(1) {
    }

    return 0 ;
}
```

2. Build a project, program the microcontroller and test the program for different RGB colors.

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III. Simple animation

1. Write a function that "shifts" the shining point on the matrix:

```
#include <stdio.h>
#include "board.h"
#include "peripherals.h"
#include "pin_mux.h"
#include "clock_config.h"
#include "LPC804.h"
#include "fsl_debug_console.h"

#define LEDS 37
#define GET_BIT(k, n) (k & (1 << (n)))
#define SET_BIT(k, n) (k |= (1 << (n)))
#define CLR_BIT(k, n) (k &= ~(1 << (n)))

#define CODE_0 0b10000
#define CODE_1 0b11100

uint32_t colors[LEDS]={0};
uint8_t k=0;
uint32_t rgbColor=0;

void Neopixels_Send(SPI_Type *base, uint32_t n, uint32_t *value) {
    uint16_t LED_data=0;

    for(int j=0;j<n;j++) {
        for(int i=23;i>=0;i--) {
            LED_data = GET_BIT(value[j], i) ? CODE_1 : CODE_0;

            while(!(base->STAT & SPI_STAT_TXRDY_MASK));
            base->TXDAT = LED_data ;
        }
        // Reset >= 50 us
        LED_data=0;
        for(int j=0;j<50;j++) {
            while(!(base->STAT & SPI_STAT_TXRDY_MASK));
            base->TXDAT = LED_data ;
        }
    }
}

inline uint32_t setRGB(uint8_t r, uint8_t g, uint8_t b) {
    return ((g<<16) | (r<<8) | b);
}

void Animate(uint32_t color)
{
    for(int j=0;j<LEDS;j++)
        colors[j]=0x000000;

    colors[k]=color;

    k++;
    if(k>=LEDS)
        k=0;
}

void SysTick_Handler(void) {
    rgbColor = setRGB(0, 0, 15); // MAX RGB: (15, 15, 15)
    Animate(rgbColor);

    Neopixels_Send(SPI0_PERIPHERAL, LEDS, colors);
}

/*
 * @brief Application entry point.
 */
int main(void) {
    /* Init board hardware. */
    BOARD_InitBootPins();
    BOARD_InitBootClocks();
    BOARD_InitBootPeripherals();
#ifdef BOARD_INIT_DEBUG_CONSOLE_PERIPHERAL
    /* Init FSL debug console. */
    BOARD_InitDebugConsole();
#endif

    SPI_WriteConfigFlags(SPI0_PERIPHERAL, kSPI_ReceiveIgnore);

    SysTick_Config(SystemCoreClock / 10); // 10 Hz

    while(1) {
    }
    return 0 ;
}
```

2. Build a project, program the microcontroller and test the program.

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IV. Animation LUT (lookup table)

1. Write an animation using the LUT table. They do not exceed the value of 15 for each RGB component!

```
#include <stdio.h>
#include "board.h"
#include "peripherals.h"
#include "pin_mux.h"
#include "clock_config.h"
#include "LPC804.h"
#include "fst_debug_console.h"

#define LEDS 37
#define GET_BIT(k, n) (k & (1 << (n)))
#define SET_BIT(k, n) (k |= (1 << (n)))
#define CLR_BIT(k, n) (k &= ~(1 << (n)))

#define CODE_0 0b10000
#define CODE_1 0b11100

uint32_t colors[LEDS]={0};
uint8_t k=0;
uint32_t rgbColor=0;

const bool pic1[4][LEDS] = {{
    0,0,0,0,
    0,0,0,0,0,
    0,0,0,0,0,0,
    0,0,0,1,0,0,0,
    0,0,0,0,0,0,
    0,0,0,0,0,
    0,0,0,0,
}, {
    0,0,0,0,
    0,0,0,0,0,
    0,0,1,1,0,0,
    0,0,1,0,1,0,0,
    0,0,1,1,0,0,
    0,0,0,0,0,
    0,0,0,0,
}, {
    0,0,0,0,
    0,1,1,1,0,
    0,1,0,0,1,0,
    0,1,0,0,0,1,0,
    0,1,0,0,1,0,
    0,1,1,1,0,
    0,0,0,0,
}, {
    1,1,1,1,
    1,0,0,0,1,
    1,0,0,0,0,1,
    1,0,0,0,0,0,1,
    1,0,0,0,0,1,
    1,0,0,0,1,
    1,1,1,1,
}};

void Neopixels_Send(SPI_Type *base, uint32_t n, uint32_t *value) {
    uint16_t LED_data=0;

    for(int j=0;j<n;j++) {
        for(int i=23;i>=0;i--) {
            LED_data = GET_BIT(value[j], i) ? CODE_1 : CODE_0;

            while(!(base->STAT & SPI_STAT_TXRDY_MASK));
            base->TXDAT = LED_data ;
        }
        // Reset >= 50 us
        LED_data=0;
        for(int j=0;j<50;j++) {
            while(!(base->STAT & SPI_STAT_TXRDY_MASK));
            base->TXDAT = LED_data ;
        }
    }
}

inline uint32_t setRGB(uint8_t r, uint8_t g, uint8_t b) {
    return ((g<<16) | (r<<8) | b);
}

void setImage(const bool *image, uint32_t color) {
    for(int i=0; i<LEDS; i++) {
        colors[i] = image[i] * color;
    }
}

void SysTick_Handler(void) {
```

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```
    rgbColor = setRGB(0, 0, 15); // MAX RGB: (15, 15, 15)
    setImage(pic1[k++ % 4], rgbColor);
    Neopixels_Send(SPI0_PERIPHERAL, LEDS, colors);
}

/*
 * @brief Application entry point.
 */
int main(void) {
    /* Init board hardware. */
    BOARD_InitBootPins();
    BOARD_InitBootClocks();
    BOARD_InitBootPeripherals();
#ifdef BOARD_INIT_DEBUG_CONSOLE_PERIPHERAL
    /* Init FSL debug console. */
    BOARD_InitDebugConsole();
#endif

    SPI_WriteConfigFlags(SPI0_PERIPHERAL, kSPI_ReceiveIgnore);

    SysTick_Config(SystemCoreClock / 5); // 5 Hz

    while(1) {
    }
    return 0 ;
}
```

2. Build a project, program the microcontroller and test the program.

3. Add another board with animation:

```
#include <stdio.h>
#include "board.h"
#include "peripherals.h"
#include "pin_mux.h"
#include "clock_config.h"
#include "LPC804.h"
#include "fsl_debug_console.h"

#define LEDS 37
#define GET_BIT(k, n) (k & (1 << (n)))
#define SET_BIT(k, n) (k |= (1 << (n)))
#define CLR_BIT(k, n) (k &= ~(1 << (n)))

#define CODE_0 0b10000
#define CODE_1 0b11100

uint32_t colors[LEDS]={0};
uint8_t k=0;
uint32_t rgbColor=0;

const bool pic1[4][LEDS] = {{
    0,0,0,0,
    0,0,0,0,0,
    0,0,0,0,0,0,
    0,0,0,1,0,0,0,
    0,0,0,0,0,0,
    0,0,0,0,0,
    0,0,0,0,
}, {
    0,0,0,0,
    0,0,0,0,0,
    0,0,1,1,0,0,
    0,0,1,0,1,0,0,
    0,0,1,1,0,0,
    0,0,0,0,0,
    0,0,0,0,
}, {
    0,0,0,0,
    0,1,1,1,0,
    0,1,0,0,1,0,
    0,1,0,0,0,1,0,
    0,1,0,0,1,0,
    0,1,1,1,0,
    0,0,0,0,
}, {
    1,1,1,1,
    1,0,0,0,1,
    1,0,0,0,0,1,
    1,0,0,0,0,0,1,
    1,0,0,0,0,0,1,
    1,0,0,0,0,1,
    1,1,1,1,
}};

const bool pic2[6][LEDS] = {{
    1,1,1,1,
    0,1,0,1,0,
    0,0,1,1,0,0,
    0,0,0,1,0,0,0,
    0,0,0,0,0,0,
    0,0,0,0,0,
    0,0,0,0,
}}
```

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```
}, {
    0,0,0,1,
    0,0,0,1,1,
    0,0,0,1,0,1,
    0,0,0,1,1,1,1,
    0,0,0,0,0,0,
    0,0,0,0,0,
    0,0,0,0,
}, {
    0,0,0,0,
    0,0,0,0,0,
    0,0,0,0,0,0,
    0,0,0,1,1,1,1,
    0,0,0,1,0,1,
    0,0,0,1,1,
    0,0,0,1,
}, {
    0,0,0,0,
    0,0,0,0,0,
    0,0,0,0,0,0,
    0,0,0,1,0,0,0,
    0,0,1,1,0,0,
    0,1,0,1,0,
    1,1,1,1,
}, {
    0,0,0,0,
    0,0,0,0,0,
    0,0,0,0,0,0,
    1,1,1,1,0,0,0,
    1,0,1,0,0,0,
    1,1,0,0,0,
    1,0,0,0,
}, {
    1,0,0,0,
    1,1,0,0,0,
    1,0,1,0,0,0,
    1,1,1,1,0,0,0,
    0,0,0,0,0,0,
    0,0,0,0,0,
    0,0,0,0,
};

void Neopixels_Send(SPI_Type *base, uint32_t n, uint32_t *value) {
    uint16_t LED_data=0;

    for(int j=0;j<n;j++) {
        for(int i=23;i>=0;i--) {
            LED_data = GET_BIT(value[j], i) ? CODE_1 : CODE_0;

            while(!(base->STAT & SPI_STAT_TXRDY_MASK));
            base->TXDAT = LED_data ;
        }
        // Reset >= 50 us
        LED_data=0;
        for(int j=0;j<50;j++) {
            while(!(base->STAT & SPI_STAT_TXRDY_MASK));
            base->TXDAT = LED_data ;
        }
    }
}

inline uint32_t setRGB(uint8_t r, uint8_t g, uint8_t b) {
    return ((g<<16) | (r<<8) | b);
}

void setImage(const bool *image, uint32_t color) {
    for(int i=0; i<LEDS; i++) {
        colors[i] = image[i] * color;
    }
}

void SysTick_Handler(void) {
    rgbColor = setRGB(0, 0, 15); // MAX RGB: (15, 15, 15)
    setImage(pic2[k++ % 6], rgbColor);
    Neopixels_Send(SPI0_PERIPHERAL, LEDS, colors);
}

/*
 * @brief Application entry point.
 */
int main(void) {
    /* Init board hardware. */
    BOARD_InitBootPins();
    BOARD_InitBootClocks();
    BOARD_InitBootPeripherals();
#ifdef BOARD_INIT_DEBUG_CONSOLE_PERIPHERAL
    /* Init FSL debug console. */
    BOARD_InitDebugConsole();
#endif

    SPI_WriteConfigFlags(SPI0_PERIPHERAL, kSPI_ReceiveIgnore);
}
```

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```
SysTick_Config(SystemCoreClock / 5); // 5 Hz  
  
while(1) {  
}  
return 0 ;  
}
```

4. Build a project, program the microcontroller and test the program.

V. Exercises

1. Create your own LUT animations
2. Create a color animation (remember not to exceed RGB values: 15, 15, 15 on many LEDs)