

ENGINE

Teaching online electronics, microcontrollers and programming in Higher Education

Programming of embedded systems

7. Przetwornik A/C

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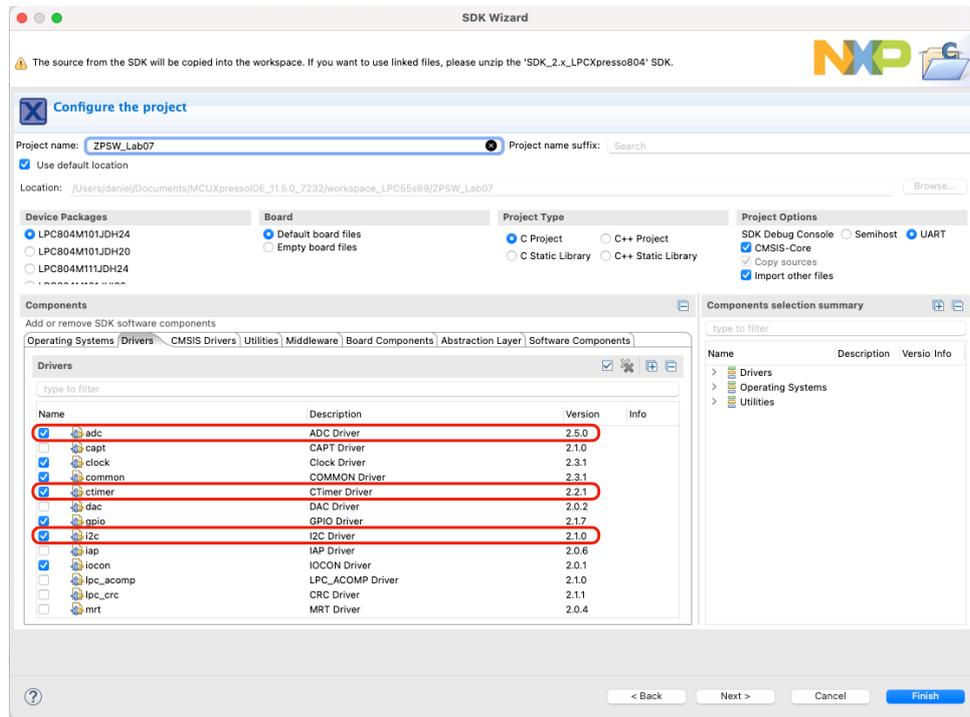
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7. Przetwornik A/C

I. Wyświetlacz OLED

1. Stwórz nowy projekt dla płyty *LPCXpresso804*. Nazwij projekt np. *ZPSW_Lab07* i dodaj sterowniki *ADC*, *CTIMER* oraz *I2C*:



2. Dodaj bibliotekę *OLED* i skonfiguruj obsługę wyświetlacza jak w poprzedniej instrukcji.
3. W *Config Tools* -> *Clocks* zmień częstotliwość generatora *FRO_OSC* na 30 MHz.
4. Przejdź do głównego pliku projektu i zmodyfikuj kod jak poniżej:

```
#include <stdio.h>
#include "board.h"
#include "peripherals.h"
#include "pin_mux.h"
#include "clock_config.h"
#include "LPC804.h"
#include "fsl_debug_console.h"
#include "oled.h"

char sbuffer[32];
volatile uint16_t adcValue = 0;

/*
 * @brief Application entry point.
 */
int main(void) {

    /* Init board hardware. */
    BOARD_InitBootPins();
    BOARD_InitBootClocks();
    BOARD_InitBootPeripherals();
#ifdef BOARD_INIT_DEBUG_CONSOLE_PERIPHERAL
    /* Init FSL debug console. */
    BOARD_InitDebugConsole();
#endif

    /* Initialize OLED */
    OLED_Init(I2C0_PERIPHERAL);

    while(1) {

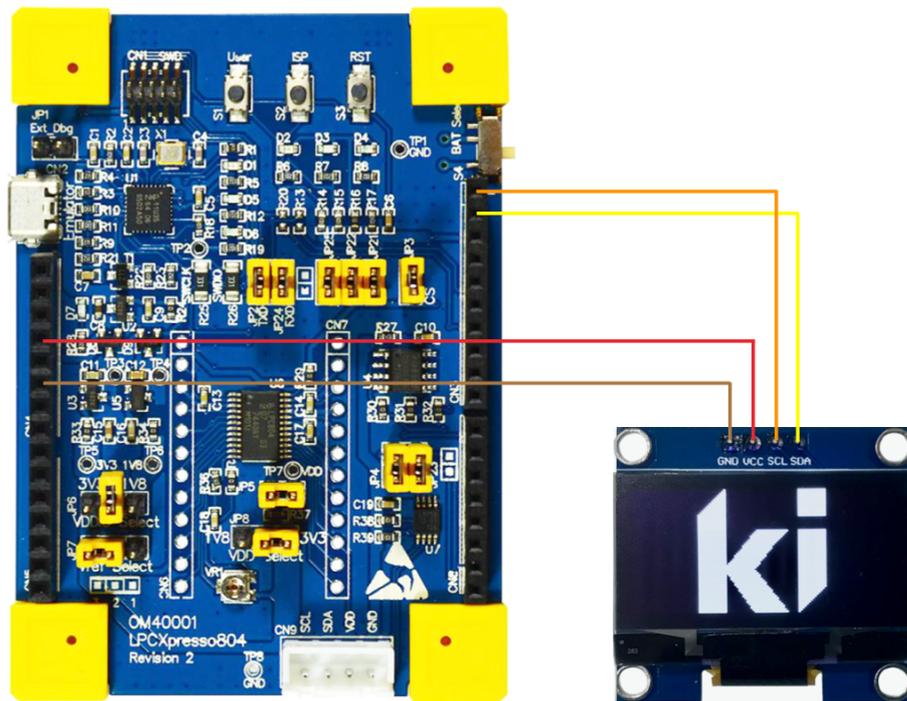
        OLED_Clear_Screen(0);
        sprintf(sbuffer, "ADC: %5d", adcValue);
        OLED_Puts(0, 1, sbuffer);
        OLED_Refresh_Gram();
    }

    return 0 ;
}
```

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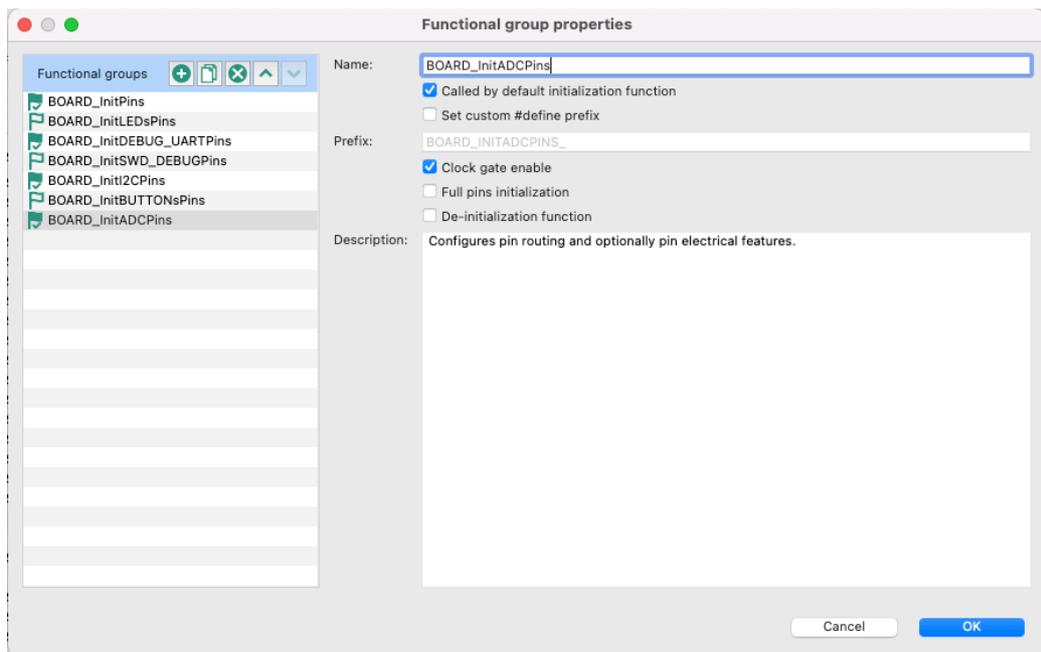
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5. Podłącz wyświetlacz i sprawdź jego działanie.



II. Przetwornik A/C

1. Przejdź do Config Tool -> Pins i utwórz nowy preset o nazwie *BOARD_InitADCPins*:



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4. Przejdź do ustawień przetwornika ADC i wprowadź poniższą konfigurację:

The screenshot displays the configuration interface for the 12-bit ADC Controller (ADC) in the MCUXpresso IDE. The main configuration area is titled "12-bit ADC Controller (ADC) [Peripheral drivers (Device specific)]".

General configuration:

- Basic ADC configuration:** Clock mode is set to "System clock", clock source frequency is "16 MHz", and clock divider number is "0".
- Configure threshold settings:** Threshold values pair 0 and pair 1 are both set to "Low value 0" and "High value 0".
- ADC conversion sequence A:** Hardware trigger is "CTIMER0_MAT3", trigger polarity is "A positive edge", and interrupt source is "Entire sequence".
- ADC conversion sequence B:** Hardware trigger is "Disabled", trigger polarity is "A negative edge", and interrupt source is "Each conversion".

Sampled channels: A table with columns for Channel number, Channel threshold pair, Threshold interrupt mode, and Conversion sequence. The table is currently empty.

Interrupt sources: Sequence A Interrupt and Sequence B Interrupt are both checked.

Enable Sequence A Interrupt: Interrupt is "ADC_SEQA_IRQn", request is "Enabled in initialization", priority is "0", and handler name is "ADC_ADC_SEQ_A_IRQHANDLER".

Enable Sequence B Interrupt: Interrupt is "ADC_SEQB_IRQn", request is "Enabled in initialization", priority is "0", and handler name is "ADC_ADC_SEQ_B_IRQHANDLER".

Enable Threshold compare interrupt: Interrupt is "ADC_THCMP_IRQn", request is "Enabled in initialization", priority is "0", and handler name is "ADC_ADC_THCMP_IRQHANDLER".

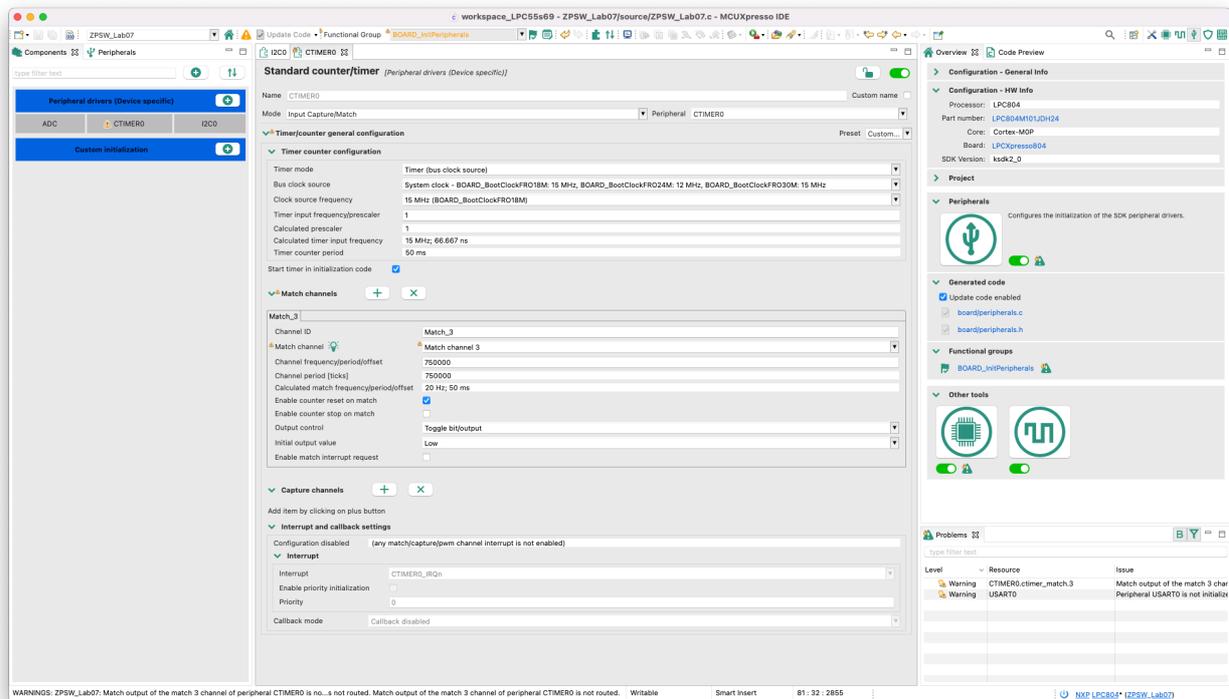
Enable Overrun error interrupt: Interrupt is "ADC_OVR_IRQn", request is "Enabled in initialization", priority is "0", and handler name is "ADC_ADC_OVR_IRQHANDLER".

Problems window: Shows two warnings: "CTIMER0.ctimer_match.3" (Match output of the match 3 char) and "USART0" (Peripheral USART0 is not initialized).

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- Przejdź do *Peripherals*, wybierz *CTIMER* i skonfiguruj go dla zmiany stanu wyjścia z częstotliwością 20 Hz:



Przetwornik ADC będzie wyzwalany tylko jednym zboczem, dlatego jego częstotliwość próbkowania będzie dwukrotnie niższa - czyli 10 Hz.

- Przejdź do głównego pliku projektu i zmodyfikuj kod jak poniżej:

```
#include <stdio.h>
#include "board.h"
#include "peripherals.h"
#include "pin_mux.h"
#include "clock_config.h"
#include "LPC804.h"
#include "fsl_debug_console.h"
#include "fsl_power.h"
#include "oled.h"

static adc_result_info_t gAdcResultInfoStruct;
adc_result_info_t *volatile gAdcResultInfoPtr = &gAdcResultInfoStruct;
char sbuff[32];
volatile uint16_t adcValue = 0;

/* ADC_SEQA_IRQn interrupt handler */
void ADC_ADC_SEQ_A_IRQHANDLER(void) {
    /* Get status flags */
    if (kADC_ConvSeqAInterruptFlag == (kADC_ConvSeqAInterruptFlag & ADC_GetStatusFlags(ADC_PERIPHERAL))) {
        /* Place your interrupt code here */
        ADC_GetChannelConversionResult(ADC_PERIPHERAL, 0, gAdcResultInfoPtr);
        adcValue = gAdcResultInfoStruct.result;
        /* Clear status flags */
        ADC_ClearStatusFlags(ADC_PERIPHERAL, kADC_ConvSeqAInterruptFlag);
    }
}

/*
 * @brief Application entry point.
 */
int main(void) {
    /* Power on ADC. */
    POWER_DisablePD(kPDRUNCFG_PD_ADC0);
    /* Init board hardware. */
    BOARD_InitBootPins();
    BOARD_InitBootClocks();
    BOARD_InitBootPeripherals();
#ifdef BOARD_INIT_DEBUG_CONSOLE_PERIPHERAL
    /* Init FSL debug console. */
    BOARD_InitDebugConsole();
#endif
}
```

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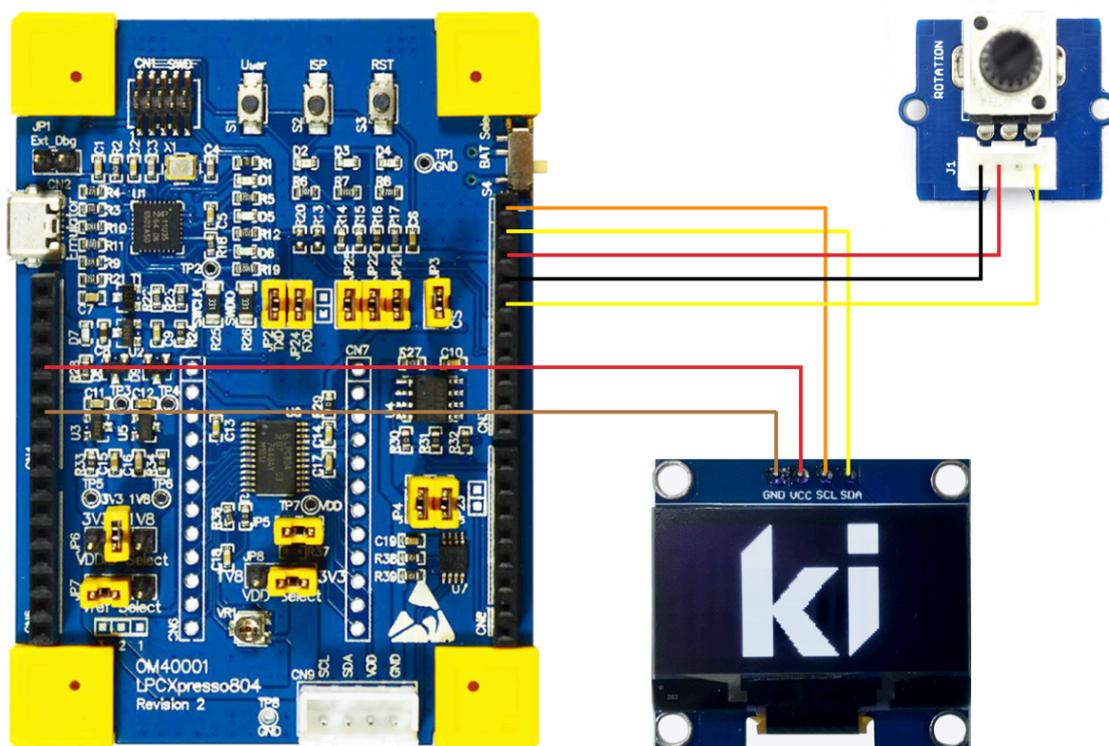
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```
#endif
/* Initialize OLED */
OLED_Init(I2C0_PERIPHERAL);

while(1) {

    OLED_Clear_Screen(0);
    sprintf(sbuff, "ADC: %5d", adcValue);
    OLED_Puts(0, 1, sbuff);
    OLED_Refresh_Gram();
}
return 0 ;
}
```

7. Podłącz potencjometr do płytki, zaprogramuj układ i sprawdź działanie przykładu. Poruszając osią potencjometru, wyświetlana wartość powinna się zmieniać w zakresie 0-4095 (12-bitowa rozdzielczość) co odpowiada napięciu wejściowemu 0-3.3 V.



III. GUI - prosty wskaźnik analogowy

1. Zmodyfikuj kod projektu:

```
#include <stdio.h>
#include "board.h"
#include "peripherals.h"
#include "pin_mux.h"
#include "clock_config.h"
#include "LPC804.h"
#include "fsl_debug_console.h"
#include "fsl_power.h"
#include "oled.h"

static adc_result_info_t gAdcResultInfoStruct;
adc_result_info_t *volatile gAdcResultInfoPtr = &gAdcResultInfoStruct;
char sbuff[32];
volatile uint16_t adcValue = 0;
float data=0;

void Gauge(uint8_t x0, uint8_t y0, uint8_t radius, float v) {

    float k= (v*270) - 135; // degrees
    float p, q=(2*PI*k)/360.0;
```

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```
uint8_t radius0 = radius * 0.9;
for(int i=-135; i<=135;i+=15) {
    p=(2*PI*i)/360.0;
    OLED_Draw_Line(x0 + radius0*sinf(p), y0 - radius0*cosf(p), x0 + radius*sinf(p), y0 - radius*cosf(p));
}
OLED_Draw_Line(x0, y0 , x0 + radius*sinf(q), y0 - radius*cosf(q));
}

/* ADC_SEQA_IRQn interrupt handler */
void ADC_ADC_SEQ_A_IRQHANDLER(void) {
    /* Get status flags */
    if (kADC_ConvSeqAInterruptFlag == (kADC_ConvSeqAInterruptFlag & ADC_GetStatusFlags(ADC_PERIPHERAL))) {
        /* Place your interrupt code here */
        ADC_GetChannelConversionResult(ADC_PERIPHERAL, 0, gAdcResultInfoPtr);
        adcValue = gAdcResultInfoStruct.result;
        /* Clear status flags */
        ADC_ClearStatusFlags(ADC_PERIPHERAL, kADC_ConvSeqAInterruptFlag);
    }
}

/*
 * @brief Application entry point.
 */
int main(void) {
    /* Power on ADC. */
    POWER_DisablePD(kPDRUNCFG_PD_ADC0);
    /* Init board hardware. */
    BOARD_InitBootPins();
    BOARD_InitBootClocks();
    BOARD_InitBootPeripherals();
#ifdef BOARD_INIT_DEBUG_CONSOLE_PERIPHERAL
    /* Init FSL debug console. */
    BOARD_InitDebugConsole();
#endif
    /* Initialize OLED */
    OLED_Init(I2C0_PERIPHERAL);

    while(1) {
        OLED_Clear_Screen(0);

        data=adcValue/4095.0;

        Gauge(64, 32, 32, data);
        sprintf(sbuff, "%3d%%", (uint8_t)(data*100));
        OLED_Puts(50, 7, sbuff);

        OLED_Refresh_Gram();
    }
    return 0 ;
}
```

2. Zbuduj projekt w trybie *Release*, zaprogramuj układ i sprawdź działanie przykładu.

IV. Zadania

1. Zmodyfikuj wygląd wskaźnika analogowego według własnego uznania.
2. Napisz funkcję rysującą n -ostatnich próbek w postaci wykresu słupkowego. Wykres ma przesuwać się po ekranie wyświetlacza (poziomu lub pionowo).