

## Teaching online electronics, microcontrollers and programming in Higher Education

# Output 2: Online Course for Microcontrollers: syllabus, open educational resources

Practice leaflet: Module\_2-2 pins as inputs

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## **Executive summary**

In this Module we will use PIC18F4550 parallel ports as inputs.

## Chapter 1: **Overview**

#### Table 1. Overview

Title / short summary	2. Use of microcontroller parallel ports as inputs
Expected learning outcomes	<ul> <li>The student will be able to define the pins of a microcontroller parallel port as inputs or outputs by using commands in C language</li> <li>The student will be able to connect switches and pull up resistors to parallel port and use it as an input</li> <li>The student will learn how to read a whole 8-bit word from a parallel input port</li> <li>The student will learn how to read the value of a pin of a parallel port that has been defined as an input.</li> <li>The student will learn how to check the value of a specific bit of a parallel input port</li> <li>The student will learn to select a different program based on the value given to an input parallel port</li> </ul>
Keywords	Direction Register, Data Register, Parallel Port, LED, switch (a){}, input(PIN_A0), bit_test(PORTD,i)

Duration	The duration of the module_2-2 is 3 hours
	• Presentation of the module_2-2 by the teacher, 30 minutes
	• 1st activity, read a binary value from PORTD and send to the PORTB the result of the read value divided by 2, 1 hour
	• 2 <sup>nd</sup> activity, program the microcontroller so that the LEDs connected to PORTB turn ON and OFF in accordance with a program selected with the switches connected on PORTD, 30 minutes
	• $3^{rd}$ activity, read the value of pin A <sub>0</sub> and the value of pin A <sub>1</sub> and turn ON an LED only when A0=1 and A1=1 (Logical function AND between A0 and A1), 30 minutes
	• 4 <sup>th</sup> activity, count the 1s of PORTD and show the result at output PORTB, 30 minutes
Involved	The teacher: Presents the slides associated with the module_2-2 and answers question
	The students:
	Draw circuits in Proteus Schematic, write programs in C language, load programs to a microcontroller and run the simulation using the Proteus Design Suite
Assignment	At the end of the Module_2-2 will be given: • Open Project
Educational tools and equipment	<ul> <li>Material: PC</li> <li>Software: CCS C compiler, Proteus Design Suite</li> </ul>

Prerequisites / pre-existing knowledge	<ul> <li>The student must know the characteristic of a LED and how to connect it to a DC source (link1)</li> <li>The student must know the use of the Direction Register and the Data Register of a microcontroller parallel port <i>PIC18F4550 datasheet (I/O ports, p. 113)</i> </li> <li>The student must know the commands of CCS C Compiler associated with the use of parallel ports <i>CCS C Compiler Manual (Built In Functions, DISCRETE I/O p. 159, set_tris_x() command p.244)</i> </li> <li>The student must be familiarized with the Proteus Design Suite (link2)</li> </ul>
Educational content	<ul> <li>CCS C Compiler manual (C Compiler Reference Manual)</li> <li>MICROCHIP, PIC18F2455/2550/4455/4550 Data Sheet</li> <li>Module_2-2 slides</li> <li>Module_2-2 Evaluation leaflet</li> <li>Module_2-2 Open project leaflet</li> <li>Module_2-2 Programs, Schematic Proteus (Compressed folder)</li> </ul>
Tips	<b>Tip1.</b> Some devices have polarity, for instance the LED, they must be connected in the right way. <b>Tip2.</b> The program must include the main.h and the 18F4550.h files. These files must be in the same folder with your project.

## Chapter 2: Activities

#### 2.1 Activity 1. Read a binary word from PORTD

The purpose of this activity is to read a binary value from PORTD and send to the PORTB the result of the read value divided by 2.

Table 2. Activity 1

Activity 1st (1 hour)	<ul> <li>Step 1. The circuit is drawn in the Proteus Design Suite. In this step 8 LEDs are connected to the PORTB parallel port. 8 switches are connected to PORTD and 8 pull up resistors.</li> <li>Step 2. The values of the resistors are calculated so that the current through the LEDs is 10mA. It is accepted that the voltage drop across the animated red LEDs is 2.2 V.</li> <li>Step 3. The program in C language is written.</li> <li>Step 4. The program is compiled with the use of CCS C compiler to the microcontroller machine code.</li> </ul>
	<ul><li>Step 5. The machine code is loaded to the microcontroller.</li><li>Step 6. The animation is activated.</li><li>Step 7. We form a binary value by closing and opening the switches</li></ul>
	<ul> <li>connected to PORTD that has been defined as input port.</li> <li>Step 8. We check that the value of PORTB, is equal to the half to the value of PORTD</li> <li>Step 7. Modifications and discussion</li> </ul>
	Step 7. Woodflications and discussion.





```
Write in CCS Compiler the program in C language
                 #include<main.h>
                 \ensuremath{{//}} This file contains the initial settings
                 // It must be in the same folder with the project
                 #byte PORTB=0xF81
                 // F81 Is the position or PORTB data register
                 // at the data memory of the microcontroller
                 // SFR Special Function Register
                 #byte PORTD=0xF83
                 // F83 Is the position or PORTB data register
                 // at the data memory of the microcontroller
                 //SFR Special Function Register
                 //*******Main program*********
                 void main()
  Step 2
                 // Opening bracket of main
(10 minutes)
                 set tris b(0x00);
                 // PORTB is set as output port
                 // (PORTB Direction Register = 0000 0000)
                 set_tris_d(0xff);
                 // PORTD is set as input port
                 // (PORTD Direction Register = 1111 1111)
                 int8 a;
                 //Definition of integer variable a
                 while(TRUE) {
                 //Endless loop(Condition always TRUE)
                 a=PORTD;
                 //Varable a takes the value or input port D
                 PORTB=a/2;
                 // Output portB takes the value a/2
                              }
                 //Closes the bracket of while
                 // Closing bracket of main
```



Step 6 (4 minutes)	<ul> <li>By turning on and off the switches form at PORTD the number 6. Check that the value that appears at PORTB is 3.</li> <li>By turning on and off the switches form at PORTD the value 255. Check that the value of PORTB is the expected one.</li> <li>By turning on and off the switches form at PORTD the value 1. Check that PORTB takes the expected value.</li> </ul>
Step 7 (17 minutes)	<ul> <li>Suggested modifications and discussion:</li> <li>Change the value of the pull up resistors to 1k. Does this create a problem? Would you prefer 10k or 1k as the value for the pull up resistors? Why?</li> <li>Change the program so that PORTB equals PORTD+2. If PORTD=254 what will be the value of PORTB? Form at PORTD the value 254 and check if the value at PORTB is in accordance with the value expected.</li> <li>Change the program so that PORTB equals 2 x PORTD. If PORTD=129 what is the expected value of PORTB. Form at PORTD the value 129 and check if the value of PORTB. Form at PORTD the value 129 and check if the value of PORTB is the expected one.</li> <li>Change the 8 switches with an 8 bit dipswitch (DIPSW_8). Check that the circuit works properly.</li> <li>If in the program we define the variable a as char a instead of int8 a, would this create a problem?</li> <li>Could we use the PORTC in the same way we used PORTD? Explain why not.</li> </ul>

# 2.2 Activity 2. LEDs on PORTB turn ON and OFF in accordance with a program selected with the switches connected on PORTD

The purpose of this activity is to program the microcontroller so that the LEDs connected to PORTB turn ON and OFF in accordance with a program selected with the switches connected on PORTD.

Activity 2 <sup>nd</sup> (30 minutes)	<ul> <li>Step 1. The circuit is drawn in the Proteus Design Suite. In this step 8 LEDs are connected to the PORTB parallel output port and 8 switches to the PORTD input port.</li> <li>Step 2. The program in C language is written.</li> <li>Step 3. The program is compiled with the use of CCS C compiler to the microcontroller machine code. The machine code is loaded to the flash memory of the microcontroller.</li> <li>Step 4. The animation is activated, and we check that the 8 LEDs turn ON and OFF in accordance with the program selected with the help of the switches.</li> </ul>
Step 1 (10 minutes)	<text></text>



```
Write in CCS Compiler the program in C language
                #include<main.h>
                //The file <main.h> contains the initial settings
                //This file must be in the same folder
                //with your project
                #byte PORTB=0xF81
                //F81 is the address of the PORTB data register
                   in the data memory of the PIC18F4550
                11
                microcontroller.
                // It's a Special Function Register (SFR)
                #byte PORTD=0xF83
                //F83 is the address of the PORTB data register
                11
                   in the data memory of the PIC18F4550
                microcontroller.
                // It's a Special Function Register (SFR)
                void main()
                // Opening bracket of main()
  Step 2
(15 minutes)
                set_tris b(0x00);
                // PORTB becomes output(Direction Register=0000
                0000)
                set tris d(0xff);
                // PORTD becomes input(Direction Register=1111
                1111)
                PORTB=0b0000000;
                // PORTB takes the initial value 0000 0000
                int a;
                // definition of integer variable a for storing
                the value of PORTD
                int i;
                // Integer variable we use inside the for
                // With the while (TRUE) { } the content inside
                the brackets
                // is executed endless
                // The word TRUE corespondes to a true condition.
                // Instead of TRUE we could use the condition 5\!\!>\!\!1
                // or any othere condition that is always true.
                while(TRUE) {
                //Eternal loop (condition always true)
```

```
a=PORTD;
//The content of PORTD data register is transfered
// to the variable a
           switch (a){
                        0:
                case
                                      PORTB=0xFF;
delay ms(100);
PORTB=0x00;
delay ms(100);
// Progran turning ON and OFF when a=0 (PORTD = % \left( \left( {{\rm PORTD}} \right) \right)
0000 0000)
break;
               case 1: PORTB=0b11000011;
delay_ms(100);
PORTB=0b00111100;
delay_ms(100);
// Progran turning ON and OFF when a=1 (PORTD =
0000 0001)
                                break;
                case 2: PORTB=0b10101010;
delay_ms(100)
;PORTB=0b01010101;delay ms(100);
// Progran turning ON and OFF when a=2 (PORTD =
0000 0010)
                               break;
                  case 3: PORTB=0b1000000; for
(i=1; i<=7; i++)
{delay_ms(50);
PORTB=PORTB/2; }
delay ms(50);
                                            Progran
                                 11
turning ON and OFF when a=3 (PORTD = 0000 0011)
                                 break;
                     case 4:
                                      PORTB=0xF0;
delay ms(100);
PORTB=0x0F;
```

	delay_ms(100);
	// Progran turning ON and OFF when $a=4$ (PORTD = 0000 0100)
	break;
	} // Closing bracket of switch ()
	<pre>} //Closing bracket of while ()</pre>
	} // Closing bracket of main ()
Step 3 (3 minutes)	Use the CCS C Compiler to translate the programm from C language to the microcontroller machine code. Load to the microcontroller the hex file (machine code) that was created from the CCS Compiler.
Step 4 (2 minutes)	Run the simulation and check by setting to PORTD the values 0, 1, 2, 3, 4 the correspondent program of turning ON and OFF the LEDs is executed.

# 2.3 Activity 3. Read the value of a specific pin of an input parallel port

The purpose of this activity is to read the value of pin A0 and the value of pin A1 and turn ON an LED only when A0=1 and A1=1 (Logical function AND between A0 and A1).

Activity 3 <sup>rd</sup> (30 minutes)	<b>Step 1.</b> The circuit is drawn at the Proteus Design Suite. In this step 2 switches are connected to the pins A0 and A1 and 1 LED to the pin D0.
	<b>Step 2.</b> The program in C language is written. The LED must be turned ON only when A0=1 and A1=1.
	<b>Step 3.</b> The program is compiled with the use of CCS C compiler to the microcontroller machine code (the hex.file is created). The

Table 4.Activity 3





//PORTD is set as output (Direction Register=0000 0000)
<pre>int1 a; // Definition of 1 bit integer for storing the value of A0 int1 b; // Definition of 1 bit integer for storing the value of A1</pre>
<pre>while(TRUE) {    //Eternal loop (condition always TRUE)         a=input(PIN_A0);         b=input(PIN_A1);</pre>
Complete the program with the necessary commands
<pre>} //Closing bracket of while() } // Closing bracket of main()</pre>

### 2.4 Activity 4. Counter of the 1s of input PORTD

The purpose of this activity is to count the 1s of PORTD and show the result at output PORTB.

Activity 4 <sup>rd</sup> (30 minutes)	<ul> <li>Step 1. The circuit is drawn in the Proteus Design Suite. In this step 8 LEDs are connected to the PORTB parallel output port and 8 switches to the PORTD input port.</li> <li>Step 2. The program in C language is written.</li> <li>Step 3. The program is compiled with the use of CCS C compiler to the microcontroller machine code. The machine code is loaded to the flash memory of the microcontroller.</li> <li>Step 4. By turning ON and OFF the switches connected to PORTD we form an 8 bit number. We check that the multitude of the 1s at PORTD is shown on PORTB</li> </ul>

Table 5.Activity 4





```
The student must complete the following program in C language.
               #include<main.h>
               // This file contains the initial settings
               // It must be in the same folder with the project
               #byte PORTB=0xF81
               // F81 Is the position or PORTB data register
               // at the data memory of the microcontroller
               // SFR Special Function Register
               #byte PORTD=0xF83
               // F83 Is the position or PORTB data register
               // at the data memory of the microcontroller
               // SFR Special Function Register
               void main()
               // Opening bracket of main
               set tris b(0x00);
  Step 2
               // PORTB is set as output port
(15 minutes)
               // (PORTB Direction Register = 0000 0000)
               set tris d(0xff);
               // PORTD is set as input port
               // (PORTD Direction Register = 1111 1111)
               PORTB=0b0000000;
               // PORTB takes the initial value of 0000 0000
               int i=0;
               // Integer varable used in the for() { }
               int a;
               // Integer varable a
               while(TRUE) {
               //Endless loop(condition always true)
                          a=0;
                          for (i=0; i<=7; i++) {
               .....
               Complete the program with the necessary
               commands .....
                                                        }
               // Closing bracket of for() { }
                          PORTB=a;
               // PORTB takes the value of the variable a
```

	<pre>// Variable a equals the multitude of 1s of PORTD         } // Closing bracket of while } // Closing bracket of main</pre>
	<b>Tip1.</b> The function $bit\_test(PORTD,i)$ checks the bit i of PORTD data register. If the bit equals to 1 then the function returns the value 1. If the bit is 0, then the function returns the value 0. <b>Tip2.</b> We can use the counter $a=a+bit\_test(PORTD,i)$ to count the 1s of PORTD
Step 3 (5 minutes)	Compile the program in order to create the hex.file (machine code). Load the program (hex.file) to the microcontroller. Check that the program shows on PORTB the multitude of the 1s of PORTD.

## Chapter 3: Recapitulation

- The schematic of the circuits was drawn with Proteus Design Suite
- The Animated LEDs were connected to the pins of the parallel output PORTB
- The Switches with pull up resistors were connected to the pins of input PORTD

The parallel PORTB of the microcontroller was defined as output and the PORTD was defined as input

Programs in C were written in CCS C compiler

The programs the value of PORTD was read as an 8-bit word or the value of a specific input pin was read

- The programs in C were compiled to the microcontroller machine code (hex file)
- The machine codes were "loaded" to the microcontroller and the animation was activated
- T was checked that the programs run properly

## References

- *CCS C Compiler Manual*. Ccsinfo.com. (2021). Retrieved from https://www.ccsinfo.com/downloads/ccs\_c\_manual.pdf.
- *PIC18F2455/2550/4455/4550 Data Sheet*. Ww1.microchip.com. (2006). Retrieved from https://ww1.microchip.com/downloads/en/devicedoc/39632c.pdf.
- *Proteus Tutorial : Getting Started with Proteus PCB Design (Version 8.6).* Youtube.com. (2017). Retrieved from <u>https://www.youtube.com/watch?v=GYAHwYUUs34</u>.
- *Simple LED Circuits*. Electronics Hub. (2017). Retrieved from <u>https://www.electronicshub.org/simple-led-circuits/</u>.



Figure 1. PORTD connected as input and PORTB as output. PORTB=PORTD/2

Build	Build & Bun	pile Target	10 10	
		PCH 16 bit v	🐝 · 🖓 ·	
			Bloduau Deprid	
	Compile	Compiler	Run	
Tex	ercise_1c.c			
1.	#includecmain.h> //This file contains the initial settings			
2		//It must be in the same folder with the project		
3	#byte PORTB-0xF81 //F81 is the position or PORTH data register			
4	Contract Accession	//at the data memory of the	microcontroller	
5	1	//SFR Special Function Regi	ster	
6	<pre>#byte PORTD=0xF83 //F83 is the position or PORTB data register // at the data memory of the microcontroller</pre>			
7				
8	1	//SFR Special Function Regi	ster	
.9				
10				
11	// ********* Main program			
12				
13	void main()			
14	日(	//Opening bracket of main		
15	<pre>set_tris_b(0x00);</pre>	//PORTS is set as output port		
16	Contraction of the second	//(PORTB Direction Register = 0000 0000)		
17	<pre>set_tris_d(0xff);</pre>	//PORTD is set as imput port		
18		//(PORTD Direction Regist	er = 1111 1111)	
19	a state of the		17.1 S 4 S 4 S 5 S 5 S 5 S 5 S 5 S 5 S 5 S 5	
20	intB a;	//Definition of integer	variable a	
21				
44				
23	E while(TRUE) {	//Indiess loop(Condition always (RUE) //Varable a takes the value or input port D		
44	a=PURID;			
20	PORISHa/2;	77 Output ports takes th	e value a/2	
20		TUCTORES THE DESCRET OF	MUTTE.	
28	1.00	17 Photos London of anti-		
		11 russing proceed of main		

Figure 2. CCS C Compiler, translation to machine code (hex file)



Figure 3. The schematic circuit of activity 2. Selection of program with the switches



Figure 4. The LED is turned ON only when A0=1 and A1=1



Figure 5. PORTB shows the multitude of the 1s of PORTD